



'Powering IoT'

EnABLES

Real Vibrations Simulation Tools

USER MANUAL

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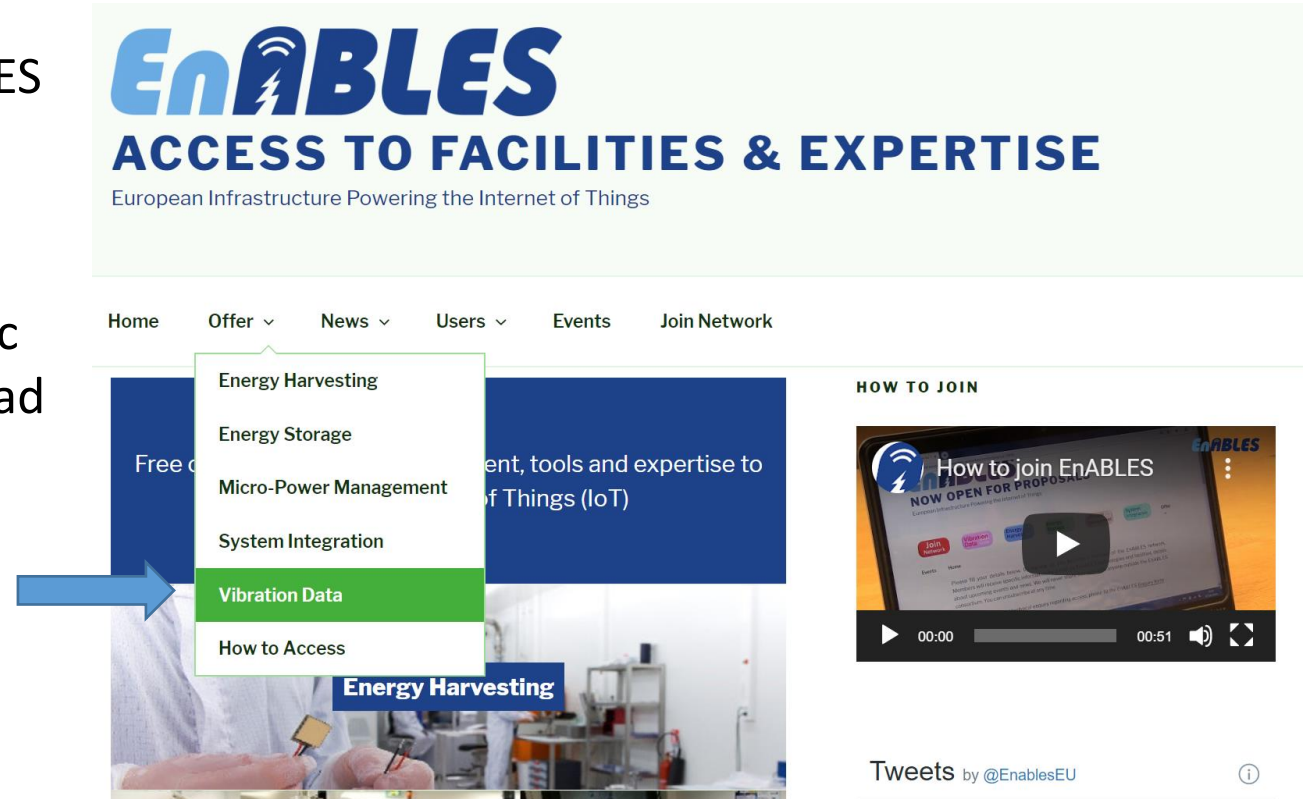


UNIVERSITÀ DEGLI STUDI
DI PERUGIA



How to access to Vibration Database

- Users are required to register from the EnABLES website <https://www.enables-project.eu/> and agree to a usage agreement.
- Users are not required to register to view basic information about the dataset, but to download raw data a login is required.
- Once registered, users are able to log in, to access data and to download as much time series data as required without restrictions.



The screenshot displays the EnABLES website interface. At the top, the EnABLES logo is followed by the tagline 'ACCESS TO FACILITIES & EXPERTISE' and the subtitle 'European Infrastructure Powering the Internet of Things'. Below this is a navigation bar with links: Home, Offer, News, Users, Events, and Join Network. The 'Offer' dropdown menu is open, showing a list of services: Energy Harvesting, Energy Storage, Micro-Power Management, System Integration, Vibration Data (highlighted in green), and How to Access. A blue arrow points to the 'Vibration Data' option. To the right of the dropdown, there is a video player titled 'HOW TO JOIN' showing a video titled 'How to join EnABLES'. Below the video player, there is a section for 'Tweets by @EnablesEU'.

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Home Offer ▾ News ▾ Users ▾ Events Join Network

Energy Harvesting DATABASES

The following data/tools are currently available:

- [Energy Harvesting Data Repository](#) (Univ. of Southampton)
- [Real Vibrations Database](#) (Univ. of Perugia)
- [Simulation Tool for Energy Harvesting Applications](#) (Univ. of Perugia)

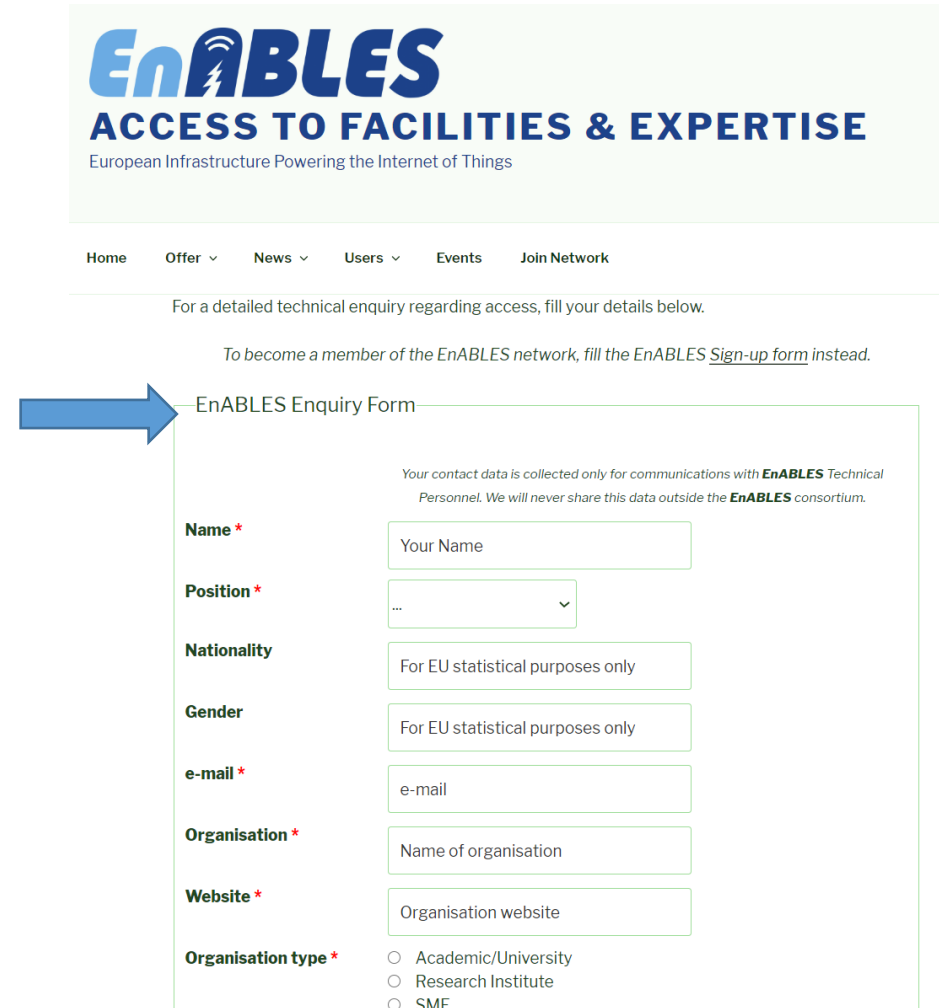
To access this data, all you have to do is register by filling the [EnABLES Enquiry Form](#), selecting **Database** as the offer of interest.

Once you have registered, please [click here](#) to access the data repository.



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The screenshot shows the EnABLES website header with the logo and tagline 'ACCESS TO FACILITIES & EXPERTISE' and 'European Infrastructure Powering the Internet of Things'. Below the header is a navigation bar with links: Home, Offer, News, Users, Events, and Join Network. A text prompt asks for details for a technical enquiry. Below this is the 'EnABLES Enquiry Form' with a blue arrow pointing to it. The form includes fields for Name, Position, Nationality, Gender, e-mail, Organisation, and Website, and a section for Organisation type with radio buttons for Academic/University, Research Institute, and SME. A disclaimer states that contact data is collected only for communications with EnABLES Technical Personnel and will not be shared outside the consortium.

EnABLES
ACCESS TO FACILITIES & EXPERTISE
European Infrastructure Powering the Internet of Things

Home Offer News Users Events Join Network

For a detailed technical enquiry regarding access, fill your details below.

To become a member of the EnABLES network, fill the EnABLES [Sign-up form](#) instead.

EnABLES Enquiry Form

Your contact data is collected only for communications with **EnABLES** Technical Personnel. We will never share this data outside the **EnABLES** consortium.

Name *

Position *

Nationality

Gender

e-mail *

Organisation *

Website *

Organisation type *

- ☐ Academic/University
- ☐ Research Institute
- ☐ SME

How to access to Vibration Database

- From the access webpage the users can choose the vibrations database developed by University of Southampton or Real Vibrations Database from University of Perugia.
- Now there is the direct link to the simulation tools totally free-of-charge for the EnABLES users.
- Currently, two main simulators are available: the general transduction-independent vibration energy harvester and piezoelectric vibration harvester. However, thi toolset is under development so that new tools will be available soon!



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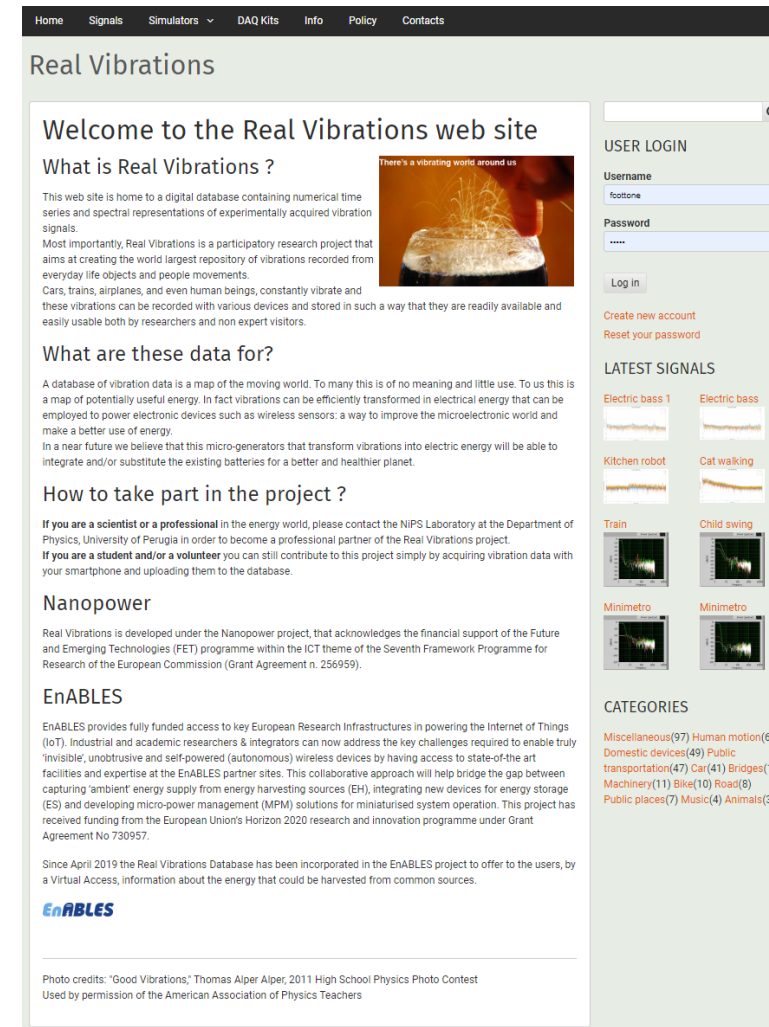
Database access interface



Real Vibration Database

- The **RealVibration** database by **NiPS/UNIPG** is contains numerical time series and spectral representations of experimentally acquired vibration signals.
- Most importantly, Real Vibrations is a **participatory research project** so that under request o the administrator users can upload their recorded vibrations from everyday life.
- It includes: **cars, trains, airplanes**, and even **human beings**, recorded with various devices and readily available and easily usable both by researchers and non expert visitors.

<https://realvibrations.nipslab.org/>



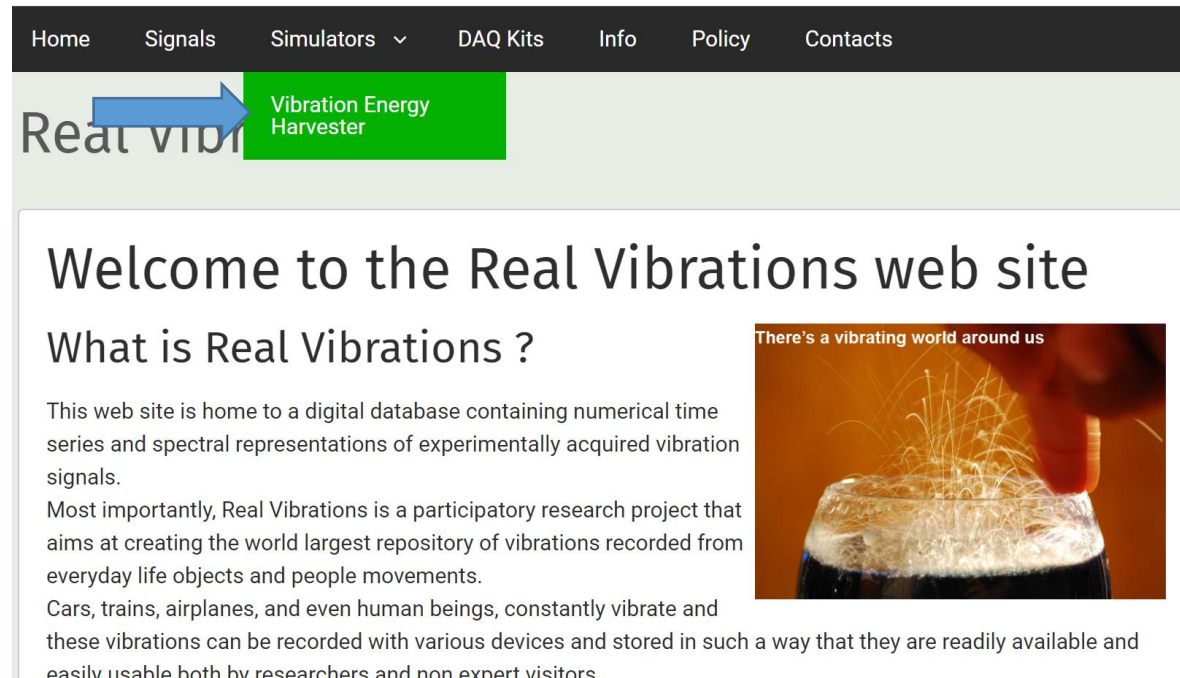
The screenshot shows the homepage of the Real Vibrations website. The header includes navigation links: Home, Signals, Simulators, DAQ Kits, Info, Policy, and Contacts. The main content area is titled "Real Vibrations" and features a welcome message, a "What is Real Vibrations?" section with a description of the database, a "What are these data for?" section explaining the project's goals, and a "How to take part in the project?" section with instructions for scientists, professionals, students, and volunteers. There are also sections for "Nanopower" and "EnABLES". The right sidebar contains a "USER LOGIN" section with fields for Username and Password, a "Log in" button, and links for "Create new account" and "Reset your password". Below this is a "LATEST SIGNALS" section displaying various vibration signals like "Electric bass", "Kitchen robot", "Cat walking", "Train", "Child swing", "Minimetro", and "Minimetro". At the bottom is a "CATEGORIES" section listing various categories and their counts.



Simulation Tools for Vibration Energy Harvesting

- **SIMULATION TOOLSET**

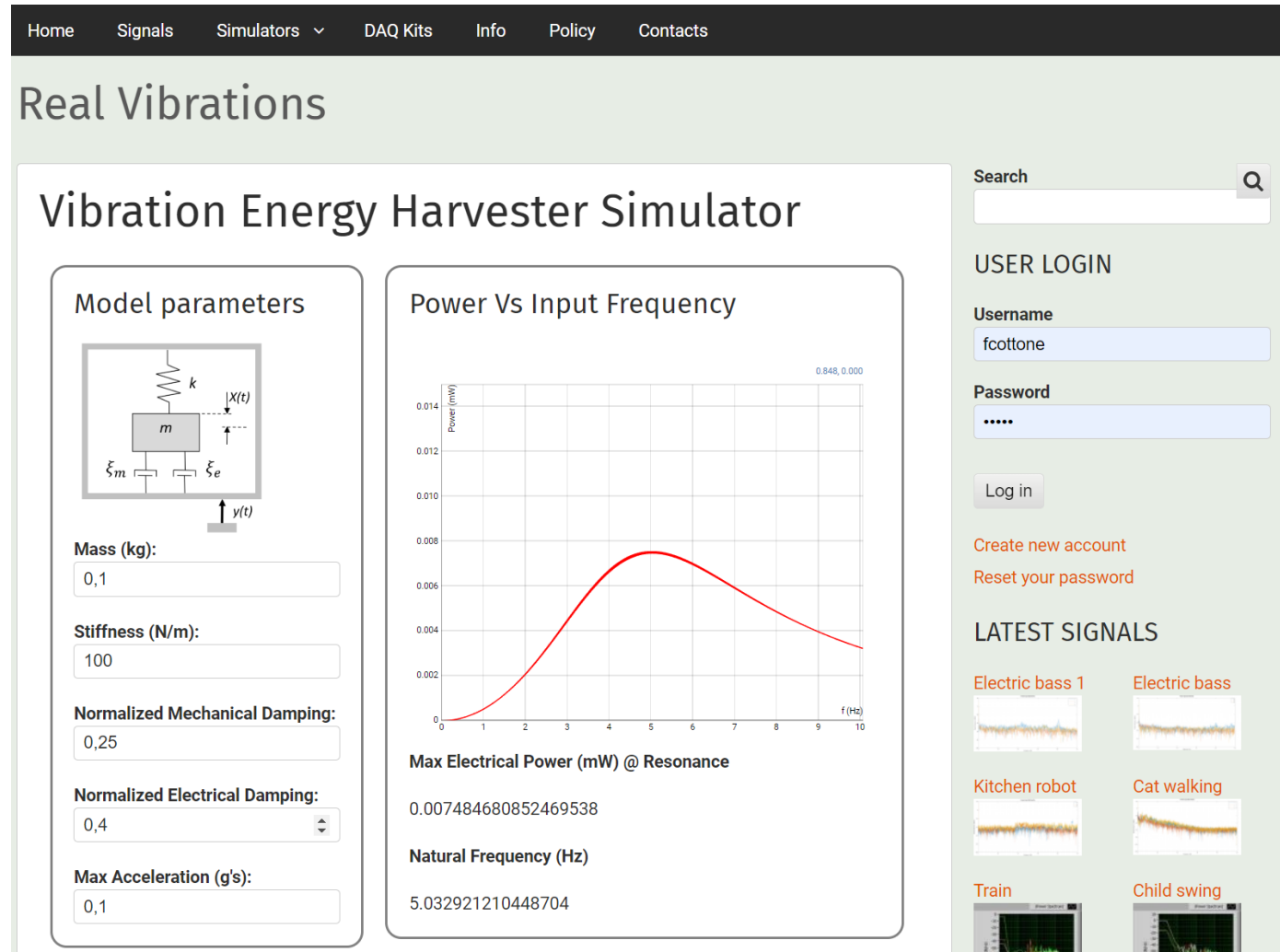
- **Vibration Energy Harvester** <https://realvibrations.nipslab.org/node/1099>
- **Piezoelectric Energy Harvester**



Simulation Tools for Vibration Energy Harvesting

<https://realvibrations.nipslab.org/node/1099>

- The first tool is a simulator of **transduction-independent vibration harvester** based on the theoretical model of William and Yates
[https://doi.org/10.1016/0924-4247\(96\)80118-X](https://doi.org/10.1016/0924-4247(96)80118-X).
- The vibration harvester is a **spring-mass-damped resonant oscillator** in which the energy conversion is accounted by the **electrical damping**.
- The user simply provides the inertial mass m , the spring equivalent stiffness k , the normalized mechanical and electrical damping ξ and the maximum input acceleration.



The screenshot displays the 'Real Vibrations' website interface. At the top is a navigation bar with links: Home, Signals, Simulators (dropdown), DAQ Kits, Info, Policy, and Contacts. The main heading is 'Real Vibrations'. Below it, the 'Vibration Energy Harvester Simulator' is featured. On the left, under 'Model parameters', there is a schematic diagram of a spring-mass-damped oscillator with a mass m , spring k , mechanical damping ξ_m , and electrical damping ξ_e . Below the diagram are input fields for: Mass (kg) (0.1), Stiffness (N/m) (100), Normalized Mechanical Damping (0.25), Normalized Electrical Damping (0.4), and Max Acceleration (g's) (0.1). On the right, under 'Power Vs Input Frequency', there is a graph of Power (mW) vs frequency f (Hz). The graph shows a resonance peak at 5.032921210448704 Hz with a maximum power of 0.007484680852469538 mW. Below the graph, the 'Max Electrical Power (mW) @ Resonance' and 'Natural Frequency (Hz)' are displayed. On the far right, there is a 'USER LOGIN' section with fields for Username (fcottone) and Password (dots), a 'Log in' button, and links for 'Create new account' and 'Reset your password'. Below this is a 'LATEST SIGNALS' section with six thumbnails: 'Electric bass 1', 'Electric bass', 'Kitchen robot', 'Cat walking', 'Train', and 'Child swing'.

Simulation Tools for Vibration Energy Harvesting

Theoretical model

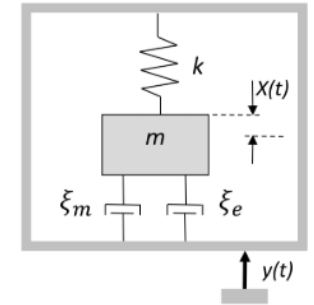
- The Newton's motion equation for an inertial generator is the following:
- where, the mechanical damping ratio is related to the mechanical and electric viscous damping, with k_t^2 and R_l being respectively the electro-mechanical transduction coefficient and the resistive load,
- by assuming a simple Harmonic excitation of input frequency $f = \omega/2\pi$ and phase $\phi = 0$,
- the electrical power versus input vibration frequency is then calculated with the following expression:

$$m\ddot{z}(t) + (d_m + d_e)\dot{z}(t) + kz(t) = -m\ddot{y}(t)$$

$$\zeta_m = \frac{d_m}{2m\omega_n}, \quad \zeta_e = \frac{k_t^2}{2m\omega_n R_l}$$

$$\ddot{y}(t) = Y_0 \sin(\omega t + \phi)$$

$$P_e(\omega) = \frac{m\zeta_e \left(\frac{\omega}{\omega_n}\right)^3 \omega^3 Y_0^2}{\left[1 - \left(\frac{\omega}{\omega_n}\right)^2\right]^2 + \left[2(\zeta_e + \zeta_m) \frac{\omega}{\omega_n}\right]^2}$$



Mass (kg):

Stiffness (N/m):

Normalized Mechanical Damping:

Normalized Electrical Damping:

Max Acceleration (g's):



Simulation Tools for Vibration Energy Harvesting

Theoretical model

- The Newton's motion equation for an inertial generator is the following:
- where, the mechanical damping ratio is related to the mechanical and electric viscous damping, with k_t^2 and R_l being respectively the electro-mechanical transduction coefficient and the resistive load,
- by assuming a simple Harmonic excitation of input frequency $f = \omega/2\pi$ and phase $\phi = 0$,
- At resonance for $\omega = \omega_n$, the maximum power is given by the following formula.
- The power can be maximized when the condition is verified

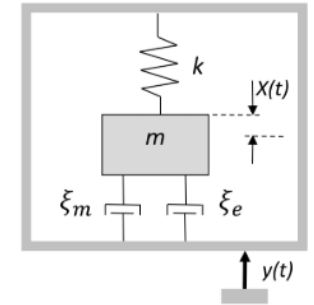
$$m\ddot{z}(t) + (d_m + d_e)\dot{z}(t) + kz(t) = -m\ddot{y}(t)$$

$$\zeta_m = \frac{d_m}{2m\omega_n}, \quad \zeta_e = \frac{k_t^2}{2m\omega_n R_l}$$

$$\ddot{y}(t) = Y_0 \sin(\omega t + \phi)$$

$$P_{max}(\omega_n) = \frac{1}{4} m \omega_n^3 Y_0^2 \frac{\zeta_e}{(\zeta_e + \zeta_m)}$$

$$\zeta_e = \zeta_m$$



Mass (kg):

Stiffness (N/m):

Normalized Mechanical Damping:

Normalized Electrical Damping:

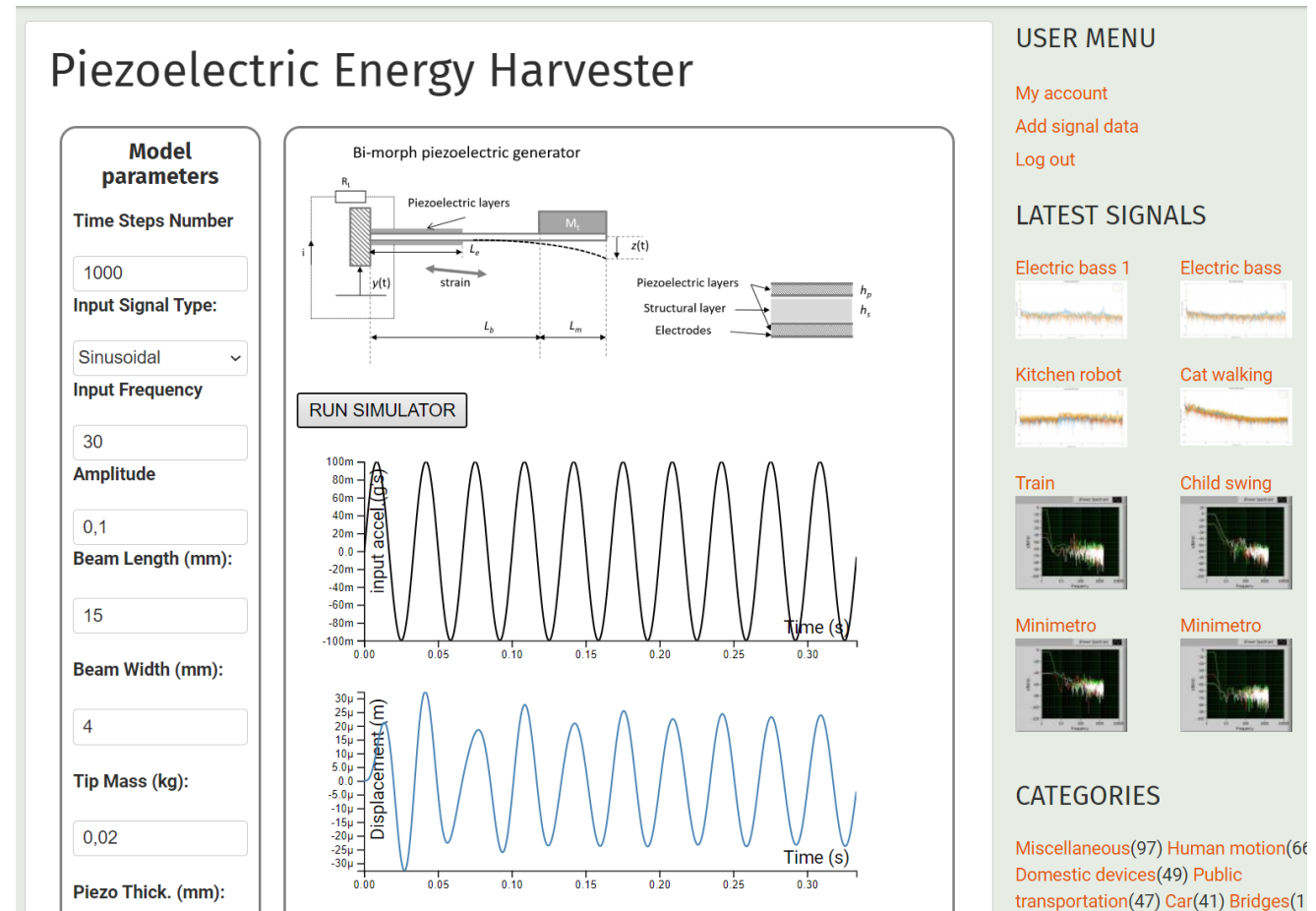
Max Acceleration (g's):





Simulation Tools for Vibration Energy Harvesting

<https://realvibrations.nipslab.org/node/1100>

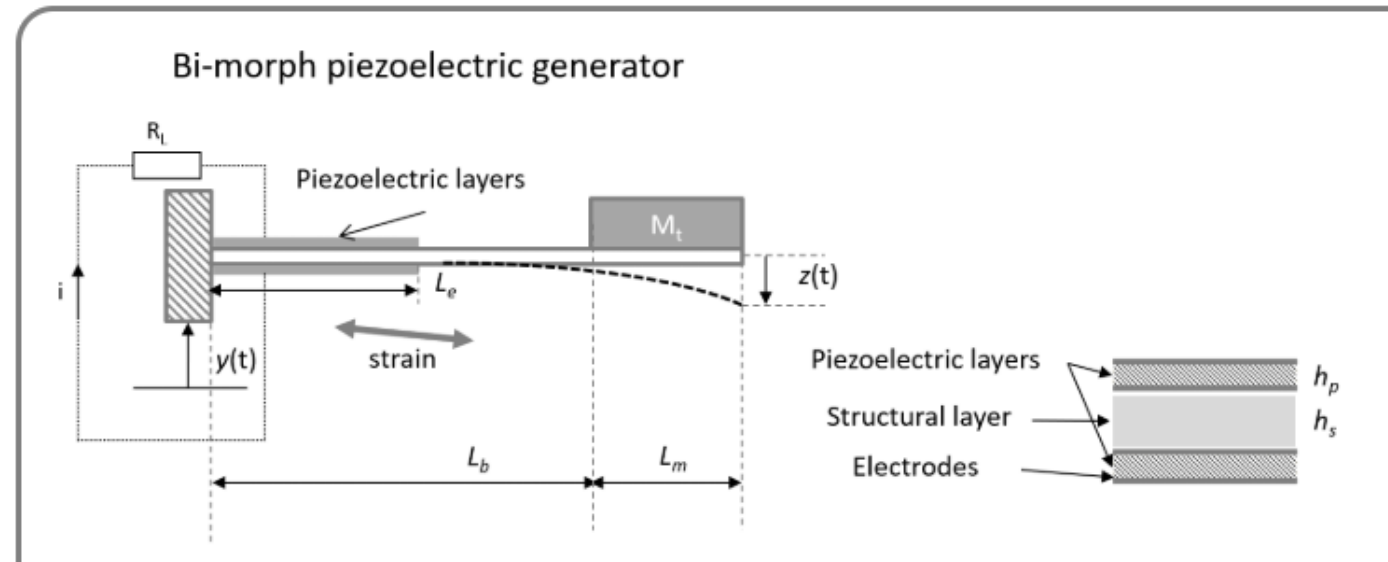
- The second tool regards the simulation of a vibrational energy harvester based on a **piezoelectric bi-morph cantilever**.
- The web application performs a numerical integration of the dynamical equations of the piezoelectric bi-morph based on theoretical model of Roundy, S., & Wright, P. K. (2004).
<https://doi.org/10.1088/0964-1726/13/5/018>; Cottone F. et al. (2015).
<https://doi.org/10.1140/epjst/e2015-02593-5>
- The user can select any signal coming from the database (even stochastic). The integration is performed with modified Euler-Maruyama with predictor-corrector algorithm.



<https://realvibrations.nipslab.org/node/1100>

| Model parameters | |
|----------------------|--|
| Time Steps Number | <input type="text" value="1000"/> |
| Input Signal Type: | <div>Database Signal </div> |
| Database Signal | <div>Car (30 s) </div> |
| Input Frequency | <input type="text" value="30"/> |
| Amplitude | <input type="text" value="0,1"/> |
| Beam Length (mm): | |
| Beam Width (mm): | <input type="text" value="4"/> |
| Tip Mass (kg): | <input type="text" value="0,02"/> |
| Piezo Thick. (mm): | <input type="text" value="0,2"/> |
| Struct. Thick. (mm): | <input type="text" value="0,1"/> |
| Mech. Damping Ratio: | <input type="text" value="0,03"/> |
| Load Resist. (ohm): | <input type="text" value="100e3"/> |

GENERATOR MODEL



Simulation Tools for Vibration Energy Harvesting

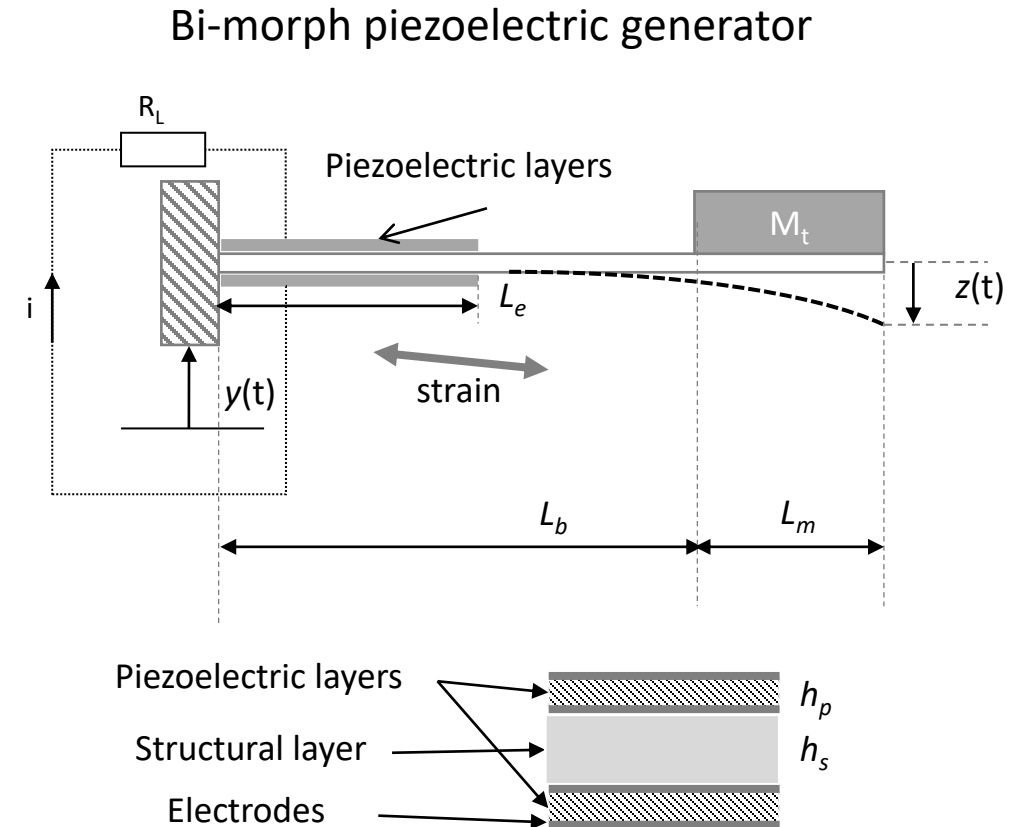
<https://realvibrations.nipslab.org/node/1100>

- The system of governing equations of the main model are derived from the Newton's and Kirchhoff's laws as follows :

$$m\ddot{z}(t) + 2\zeta_m\omega_n\dot{z}(t) + kz(t) + k_vV(t) = -m\ddot{y}(t)$$

$$\dot{V}(t) + \frac{1}{R_l C_p} V(t) = k_c \dot{z}(t)$$

- where the k_v , k_c and C_p represent the electro-mechanical transduction coefficient, the velocity-voltage coefficient and the equivalent capacitance of the piezoelectric beam. These parameters are derived from the particular geometry and electrical properties of the piezoelectric generator: such as beam length, width, thickness and piezoelectric constant of the material.



Simulation Tools for Vibration Energy Harvesting

<https://realvibrations.nipslab.org/node/1100>

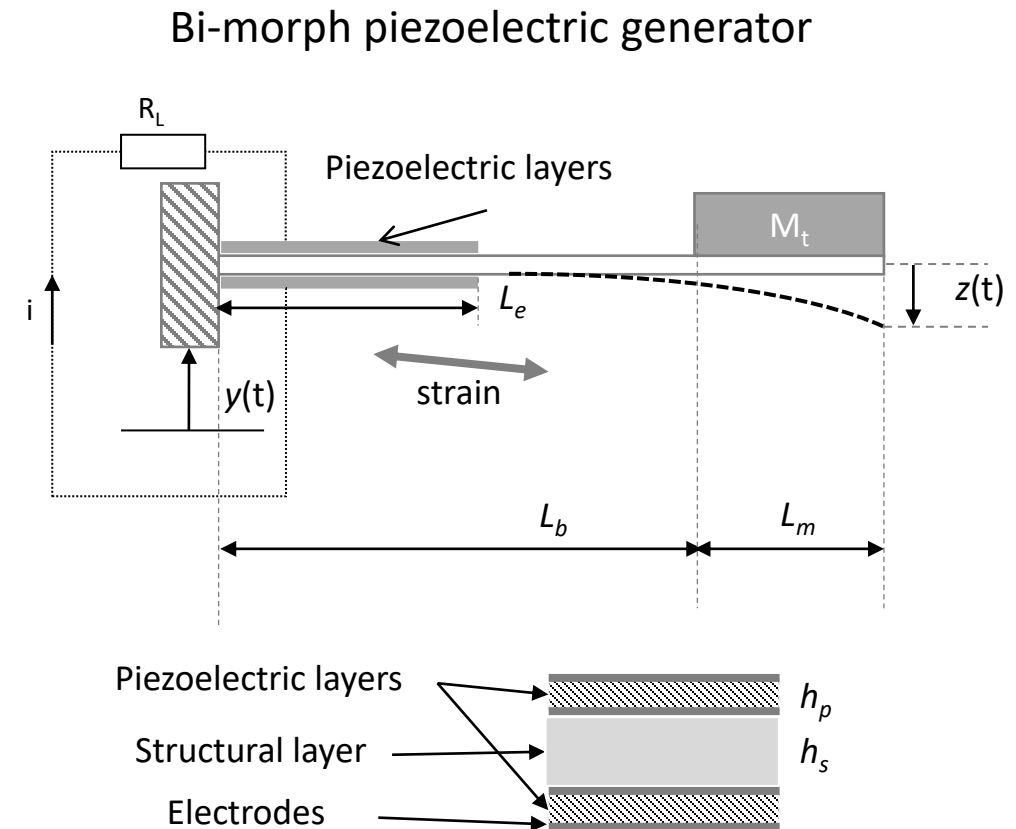
- The **dependent parameters** are derived from the **input parameters** as the paper of Roundy [1] and Cottone [2].

$$k_v = kd_{31}/h_p k_2 \quad \text{Electro-mechanical transduction coefficient}$$

$$k_c = 2h_p d_{31} E_p k_2 / (a e_p) \quad \text{Voltage to velocity coefficient}$$

$$k_1 = \frac{2I}{b(2L_b + L_m - L_e)} \quad \text{Average strain to input force}$$

$$k_2 = \frac{3b(2L_b + L_m - L_e)}{L_b^2 \left(2L_b + \frac{3}{2}L_m \right)} \quad \text{Average strain to vertical displacement}$$



[1] Roundy, S., & Wright, P. K. (2004). <https://doi.org/10.1088/0964-1726/13/5/018>

[2] Cottone, F. et al. (2015). <https://doi.org/10.1140/epjst/e2015-02593-5>

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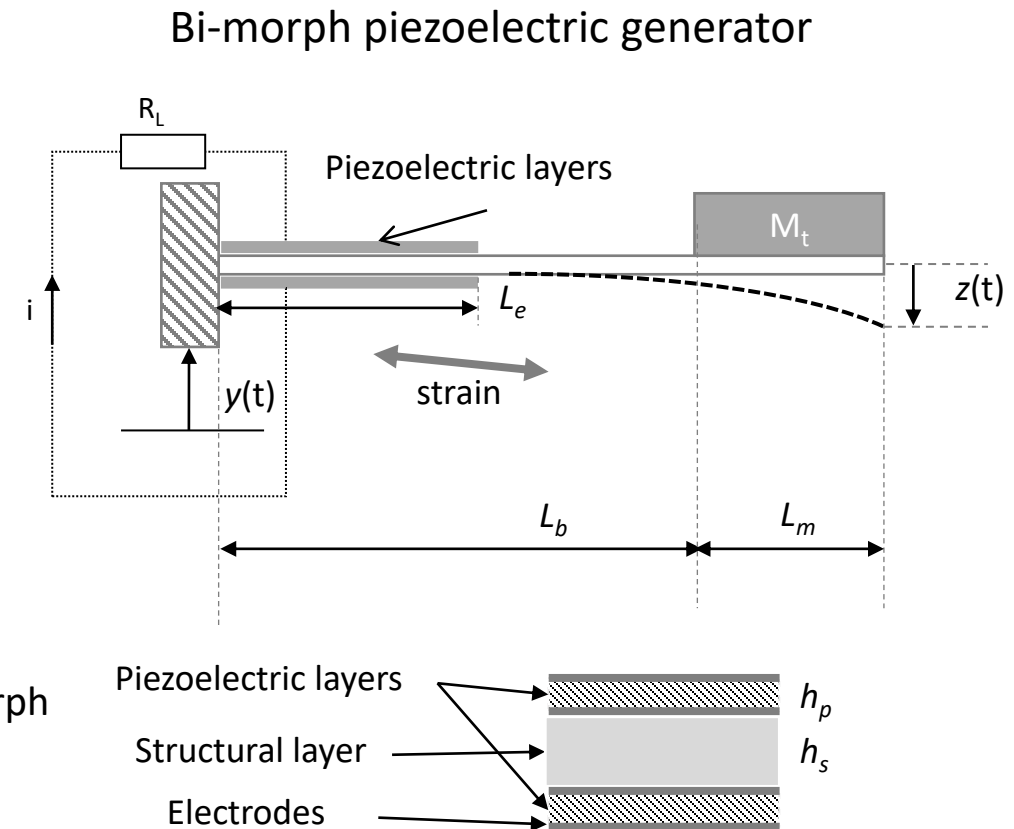
$$I = 2 \left(\frac{w_b h_p^3}{12} + w_b h_p b^2 \right) + \frac{1}{12} \left(\frac{E_p}{E_{sh}} w_b h_{sh}^3 \right) \quad \text{Beam area inertia moment}$$

$$K = E_p k_2 k_1 \quad \text{Equivalent spring constant of the beam}$$

$$C_p = \frac{a^2 e_p w_b L_e}{2 h_p} \quad \text{Equivalent capacitance of piezoelectric beam}$$

$a = 1$ or 2 It is equal to 1 for series and 2 for parallel connection of the bi-morph

$$b = \frac{h_p}{2} + \frac{h_{sh}}{2} \quad \text{distance between structural and piezoelectric layer}$$



[1] Roundy, S., & Wright, P. K. (2004). <https://doi.org/10.1088/0964-1726/13/5/018>

[2] Cottone, F. et al. (2015). <https://doi.org/10.1140/epjst/e2015-02593-5>